MECHANICS OF SOLIDS (ME F211)

## Mechanics of Solids

## Chapter-8

## Deflections due to Bending

## Contents:

$\square$ The moment curvature relation
Integration of moment curvature relation
$\square$ Principle of Superposition
$\square$ Load- deflection differential equation
$\square$ Energy methods

## Deflections due to Bending

## The moment curvature relation

The relation between curvature of neutral axis and bending moment is given by

$$
\frac{1}{\rho}=\lim _{\Delta s \rightarrow 0} \frac{\Delta \phi}{\Delta s}=\frac{d \phi}{d s}=\frac{M_{b}}{E I_{z z}}
$$

$\square E$ is modulus of elasticity and $I_{z z}$ is moment of inertia.
Longitudinal dimension of the beam will be in $x$ direction.
$\square$ Bending will take place in $x y$ plane about $z$ axis.
$\square$ Instead of symbol $I_{z z}$ for moment of inertia, we use the abbreviation $/$.


Deformation of an element of a beam subjected to bending moments $M_{b}$

## Deflections due to Bending

## The moment curvature relation

Deflection of neutral axis from the knowledge of its curvature Slope of the neutral axis

$$
\frac{d v}{d x}=\tan \phi
$$

Differential with arc length $s$.

$$
\begin{aligned}
& \frac{d^{2} v}{d x^{2}} \frac{d x}{d s}=\sec ^{2} \phi \frac{d \phi}{d s} \\
& \frac{d \phi}{d s}=\frac{d^{2} v}{d x^{2}} \frac{d x}{d s} \cos ^{2} \phi
\end{aligned}
$$



Geometry of the neutral axis of a beam bent in the $x y$ plane

## Deflections due to Bending

## The moment curvature relation

## From Figure

$$
\cos \phi=\frac{d x}{d s}=\frac{1}{\left[1+(d v / d x)^{2}\right]^{1 / 2}}
$$

The curvature is

$$
\frac{d \phi}{d s}=\frac{d^{2} v / d x^{2}}{\left[1+(d v / d x)^{2}\right]^{3 / 2}}
$$



Geometry of the neutral axis of a beam bent in the $x y$ plane

## Deflections due to Bending

## The moment curvature relation

$$
\frac{d \phi}{d s}=\frac{M_{b}}{E I_{z z}} \quad \Rightarrow \quad \frac{d^{2} v / d x^{2}}{\left[1+(d v / d x)^{2}\right]^{3 / 2}}=\frac{M_{b}}{E I}
$$

$\square$ Above equation is nonlinear differential equation for determination of $v$ as a function of $x^{2}$, if $M_{b}$ is known.
$\square$ When the slope angle $\phi$ is small, then $d v / d x$ is small compared to unity

$$
\frac{d \phi}{d s} \approx \frac{d^{2} v}{d x^{2}} \quad \frac{d^{2} v}{d x^{2}}=\frac{M_{b}}{E I} \quad-----1
$$

$\square$ Equation 1 is called moment curvature relation
$\square$ The term El is referred as flexural rigidity or bending modulus.

## Deflections due to Bending

## Integration of the moment curvature relation

- Integration of moment curvature relation leads to the correct deflection curve.
$\square$ However suitable boundary conditions should be chosen to determine the integration constants.
$\square$ Figure shows the suitable boundary condition encountered in various supports.



## Deflections due to Bending

## Problem:

The simply supported beam of uniform cross section shown in figure is subjected to a concentrated load $W$. It is desired to obtained maximum slope and maximum deflection.


## Deflections due to Bending

## Solution:

$\square$ Singularity function method is used to find bending moment.
The maximum deflection is the point at which the slope is zero.
Therefore maximum deflection will be at $x=L / 2$.
$\square$ Maximum slope will be at $x=0$ or at $x=L$.

Maximum Deflection $v_{\text {max }}$ will be

$$
v_{\max }=(v)_{x=L / 2}=-\frac{W L^{3}}{48 E I}=5.19 \mathrm{~mm}
$$

Maximum slope $\phi_{\max }$ will be $\phi_{\max }=\left(\frac{d v}{d x}\right)_{x=0}=-\frac{W L^{2}}{16 E I}=-0.0042$ rad $=0.24^{\circ}$

## Deflections due to Bending

## Problem:

A uniform cantilever beam has bending modulus $E I$ and length $L$. It is built in at $A$ and subjected to a concentrated force $P$ and moment $M$ applied at B as shown in figure. Find deflection $\delta$ and slope $\phi$ at point $B$.


## Deflections due to Bending

## Solution:

D Deflection $\delta$ at point $B$ will be

$$
\delta_{B}=-(v)_{x=L}=\frac{P L^{3}}{3 E I}+\frac{M L^{2}}{2 E I}
$$

[ Deflection $\phi$ at point $B$ will be

$$
\phi_{B}=-\left(\frac{d v}{d x}\right)_{x=L}=\frac{P L^{2}}{2 E I}+\frac{M L}{E I}
$$



## Deflections due to Bending

## Superposition

The total deflection is the sum of deflections due to individual load ( $M_{b}$ )

- The deflections in the standard cases are given in table 8.1. The solution of the original problem then takes the form of a superposition of these solutions.
$\square$ Deflection of a beam is linearly proportional to the applied load
The linearity between curvature and deflection is based on assumption that
- Deflections are small
- material is linearly elastic


## Deflections due to Bending

## Problem:

The cantilever beam shown in figure carries a concentrated load $P$ and end moment $M_{o}$ applied at B as shown in figure. Find deflection $\delta$ at point $C$ in terms of the constant bending modulus $E I$.


## Deflections due to Bending

## Solution:



## Deflections due to Bending

## The Load-Deflection Differential Equation

- An alternative method to solve beam deflection problem.
$\square$ The differential equations for force and moment equilibrium are

$$
\frac{d V}{d x}+q=0 \quad \text { and } \quad \frac{d M_{b}}{d x}+V=0
$$

Therefore,

$$
\frac{d^{2} M_{b}}{d x^{2}}=q
$$

$\square$ Using above equation and moment curvature relation, we obtained a single differential equation relating transvers load-intensity function $q$ and transverse deflection $v$.

$$
\frac{d^{2}}{d x^{2}}\left(E I \frac{d^{2} v}{d x^{2}}\right)=q
$$

## Deflections due to Bending

## Boundary Conditions

$\square$ Figure shows the suitable boundary conditions corresponds to four types of supports.


## Deflections due to Bending

## Problem

The beam shown in figure is built-in at $A$ and $D$ and has an offset arm welded to the beam at the point $B$ with a load $W$ attached to the arm at $C$. It is required to find the deflection of the beam at the point $B$.


## Deflections due to Bending

## Solution

Load intensity

$$
q=\frac{W L}{3}\langle x-L / 3\rangle_{-2}-W\langle x-L / 3\rangle_{-1}
$$

Boundary conditions

$$
v=0 \text { and } \frac{d v}{d x}=0 \quad \text { at } x=0 \text { and } L
$$

Load-deflection differential equation

$$
E I \frac{d^{4} v}{d x^{4}}=W\left(\frac{L}{3}\langle x-L / 3\rangle_{-2}-\langle x-L / 3\rangle_{-1}\right)
$$



## Deflections due to Bending

## Solution

By integrating previous equation

$$
\frac{d v}{d x}=\frac{W}{E I}\left(\frac{L}{3}\langle x-L / 3\rangle^{1}-\frac{\langle x-L / 3\rangle^{2}}{2}+c_{1} \frac{x^{2}}{2}+c_{2} x+c_{3}\right)
$$

$$
v=\frac{W}{E I}\left(\frac{L}{6}\langle x-L / 3\rangle^{2}-\frac{\langle x-L / 3\rangle^{3}}{6}+c_{1} \frac{x^{3}}{6}+c_{2} \frac{x^{2}}{2}+c_{3} x+c_{4}\right)
$$

Boundary conditions gives four integration constants

$$
c_{1}=\frac{8}{27} ; \quad c_{2}=-\frac{4}{27} L ; \quad c_{3}=c_{4}=0
$$

## Deflections due to Bending

## Solution

By inserting boundary conditions in deflection equation

$$
v=\frac{W}{27 E I}\left(\frac{9}{2} L\langle x-L / 3\rangle^{2}-\frac{9}{2}\langle x-L / 3\rangle^{3}+\frac{4}{3} x^{3}-2 L x^{2}\right)
$$

Deflection at point $B$, by setting $x=L / 3$

$$
\delta_{B}=-(v)_{x=L / 3}=\frac{14 W L^{3}}{2187 E I}
$$

## Deflections due to Bending

## Castigliano's Method to find the deflections

$\square$ Strain energy due to transverse loads

$$
\begin{aligned}
& U=\frac{1}{2} \iiint_{x} \sigma_{x} \varepsilon_{x} d x d y d z=\iiint_{x} \frac{\sigma_{x}^{2}}{2 E} d x d y d z \\
& U=\iiint_{L} \frac{1}{2 E}\left(\frac{M_{b} y}{I}\right)^{2} d x d y d z=\int_{L} \frac{M_{b}^{2}}{2 E I^{2}} d x \iint_{A} y^{2} d y d z \\
& U=\int_{L} \frac{M_{b}^{2}}{2 E I} d x
\end{aligned}
$$

$\square$ If total elastic energy in a system is expressed in terms of external loads $P_{i}$, the corresponding in-line deflections $\delta_{i}$ are given by partial derivatives

$$
\delta_{i}=\frac{\partial U}{\partial P_{i}}
$$

## Castigliano's Method to find the deflections

Important
$\square$ If, we may wish to know deflection at a point where external force is zero .
$\square$ In such case a fictitious force $Q$ is to be considered at that point.
$\square$ Deflection at that point in the direction of $Q$ is given by $\partial \mathrm{U} / \partial Q$ and setting $Q=0$.

Similarly slope is given by

$$
\phi=\frac{\partial U}{\partial M}
$$

## Deflections due to Bending

## Castigliano's Method to find the deflections

Simplified equation

- Deflection

$$
\delta_{i}=\frac{\partial U}{\partial P_{i}}=\int_{0}^{L} \frac{2 M_{b}}{2 E I} \frac{\partial M_{b}}{\partial P_{i}} d x=\int_{0}^{L} \frac{M_{b}}{E I} \frac{\partial M_{b}}{\partial P_{i}} d x
$$

$\square$ Slope

$$
\phi_{i}=\frac{\partial U}{\partial M_{i}}=\int_{0}^{L} \frac{2 M_{b}}{2 E I} \frac{\partial M_{b}}{\partial M_{i}} d x=\int_{0}^{L} \frac{M_{b}}{E I} \frac{\partial M_{b}}{\partial M_{i}} d x
$$

## Deflections due to Bending

## Problem

Using Castigliano's method, determine the slope and deflection at point $B$ (loading diagram is shown in figure below).


## Deflections due to Bending

Solution
Bending moment $=M_{b}=-P(L-x)-M \quad$ and $\quad \frac{\partial M_{b}}{\partial P}=-(L-x)$

Deflection at point $B$ will be

$$
\delta_{B}=\frac{\partial U}{\partial P}=\int_{0}^{L} \frac{2 M_{b}}{2 E I} \frac{\partial M_{b}}{\partial P_{i}} d x=\int_{0}^{L} \frac{M_{b}}{E I} \frac{\partial M_{b}}{\partial P} d x
$$

After solving above equation

$$
\delta_{B}=\frac{P L^{3}}{3 E I}+\frac{M L^{2}}{2 E I}
$$

## Deflections due to Bending

Solution
Bending moment $=M_{b}=-P(L-x)-M$ and

$$
\frac{\partial M_{b}}{\partial M}=-1
$$

Slope at point $B$ will be

$$
\phi_{B}=\frac{\partial U}{\partial M}=\int_{0}^{L} \frac{2 M_{b}}{2 E I} \frac{\partial M_{b}}{\partial M} d x=\int_{0}^{L} \frac{M_{b}}{E I} \frac{\partial M_{b}}{\partial M} d x
$$

After solving above equation

$$
\phi_{B}=\frac{P L^{2}}{2 E I}+\frac{M L}{E I}
$$

## Deflections due to Bending

## Problem

Using Castigliano's method, determine the reaction at point $A$.
Take $a=b=L / 2$


## Deflections due to Bending

## Solution

We know that deflection at point A is zero. Let's find reaction at $A$.

Bending moment $=M_{b}=R_{A} x-P\langle(x-a)\rangle^{1}$ and

$$
\frac{\partial M_{b}}{\partial R_{A}}=x
$$

Deflection at point $A$ will be

$$
\begin{gathered}
\delta_{A}=\int_{0}^{L} \frac{M_{b}}{E I} \frac{\partial M_{b}}{R_{A}} d x=0 \\
\delta_{A}=0=\frac{1}{E I} \int_{0}^{L}\left(R_{A} x^{2}-P x<x-\frac{L}{2}>\right) d x
\end{gathered}
$$

## Deflections due to Bending

## Solution

$$
\left.0=R_{A}\left[\frac{x^{3}}{3}\right]_{0}^{L}-P[x]\left\langle x-\frac{L}{2}\right\rangle-\int \frac{d x}{d x} \int\left\langle x-\frac{L}{2}\right\rangle\right]_{0}^{L}
$$

$$
0=\frac{R_{A} L^{3}}{3}-\frac{5 P L^{3}}{48}
$$

$$
R_{A}=\frac{5}{16} P
$$

## Deflections due to Bending

## Problem

Using Castigliano's method, determine horizontal deflection at point A (consider deflection due to only bending moments).


ANS. $\delta_{A}=\frac{13 P L^{3}}{192 E I}$

## Deflections due to Bending

## References

1. Introduction to Mechanics of Solids by S. H. Crandall et al (In SI units), McGraw-Hill
